

# API Development Manual:

## AMTFaceLite SDK For Windows

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ARMATURA biometric hardware and software are incorporated into the product designs of some of the world's leading suppliers of workforce management (WFM) terminals, Point-of-Sale (PoS) terminals, intercoms, electronic safes, metal key lockers, dangerous machinery, and many other products which heavily rely on correctly verifying & authenticating user's identity.

## About the Manual

This manual introduces the operations of **AMTFaceLite SDK For Windows**.

All figures displayed are for illustration purposes only. Figures in this manual may not be exactly consistent with the actual products.






## Document Conventions

Conventions used in this manual are listed below:

### GUI Conventions

For Software	
Convention	Description
<b>Bold font</b>	Used to identify software interface names e.g. <b>OK</b> , <b>Confirm</b> , <b>Cancel</b> .
>	Multi-level menus are separated by these brackets. For example, File > Create > Folder.
For Device	
Convention	Description
<>	Button or key names for devices. For example, press <OK>.
[ ]	Window names, menu items, data table, and field names are inside square brackets. For example, pop up the [New User] window.
/	Multi-level menus are separated by forwarding slashes. For example, [File/Create/Folder].

### Symbols

Convention	Description
	This represents a note that needs to pay more attention to.
	The general information which helps in performing the operations faster.
	The information which is significant.
	Care taken to avoid danger or mistakes.
	The statement or event that warns of something or that serves as a cautionary example.

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# 1 Introduction

This document will provide with basic SDK development guide and technical background to help with better use of our AMTFaceLite SDK document. From the perspective of a developer, the key design objective of this SDK is its compatibility and ease of execution.

This development manual contains the product development documentation for developers that describes the functions provided by the SDK and its related usage, which eases the development environment.

The following sections explain all the required information on how to perform and integrate AMTFaceLite SDK.

## 1.1 Overview of the SDK

AMTFaceLite SDK is a wrapper of Armatura near-Infrared light face recognition algorithm. It is an excellent near-infrared face recognition algorithm based on the indoor face recognition algorithm, developed to resist complex ambient light and the needs of large capacity recognition. In the case of ensuring a very low FRR, the algorithm focuses on improving the wide adaptation to the environment and user habits, thereby greatly improving the robustness and success rate of face recognition.

The SDK provides the rich interfaces to access the algorithm's functionalities for face recognition process, including face detection, feature extraction, liveness detection, template creation, and face identification.

The FaceLite SDK utilizes the widely supported libusb API for face module communication, supports common-used operation systems, and frees the developers from intimidating hardware operations. It is a developer-friendly toolkit to empower the biometric features on the software application with easy pickup.

The simple library components aid in supporting and enhancing the security requirements through biometric facial recognition which avoids spoofing and has been widely used in various systems, including attendance, security, video monitoring, and so on.

## 1.2 Feature of the SDK

- **Face Focusing Method to Enhance Image Quality:**

The FaceLite algorithm takes face focusing method to enhance the image quality which significantly reduces the facing-light and back-light impact on the captured image.

- **Stable Face Features Boost Recognition Accuracy and Performance**

The FaceLite algorithm can detect different levels (18,40 or 120) of key face feature points and their positions in milliseconds, such as eyes, lips, nose tips, and contours. Such key points are stable face features and can be recognized from the deliberated and unintentional variations in the captured face images. It boosts the algorithm to achieve face recognition accuracy and performance.

- **Multi-dimensional Face Feature Template for Robust Face Recognition:**

The FaceLite algorithm calculates multi-dimensional features from the collected multiple templates (5 consecutive templates) to generate one enrollment template which minimizes the side impact from hats, scarves, dark glasses, or other attachments during the registration process. This improves the recognition robustness.

- **Liveness Detection:**

The FaceLite algorithm can effectively detect a fake face from a digital photo, printed color photo, Black & White face image, or a recorded video of a live face.

- **High Recognition Performance**

Based on the stable face features, the FaceLite algorithm takes the multi-level matching mode with optimized classifier parameters to match the candidate in the large-volume template library within a second.

- **Automatic Update the Template Library:**

The FaceLite algorithm tracks face features and automatically updates the face template into the template library, such an adaptive approach can keep the template stay with the user's current appearance and lower the rejection rate caused by changes in the user's appearance and hairstyle.



- **Algorithm Integrity:**

Combined with Armatura near-infrared light face module, the FaceLite algorithm ensures the quality of images by maintaining data integrity for a genuine and accurate image process.

## 1.3 Advantage of the SDK

- Easy to use by other developers.
- Thorough documentation to explain how your code works.
- Enough functionality so it adds value to other applications.
- Does not negatively impact.
- Plays well with other SDKs.

## 2 Technical Specifications

### Development Language

This SDK provides a standard Win32 API interface and supports C, C++, and C# language development.

### Platform Requirements

This SDK supports 32-bit/64-bit operating systems with Windows XP SP3 or higher.

### Technical Parameters

Parameter	Description
Template size	< 29 KB
Gesture adaptability	Yaw $\leq 25^\circ$ , Pitch $\leq 25^\circ$ , Roll $\leq 25^\circ$
Face detection	< 80 ms
Face feature extraction	< 100 ms
Face verification/identification (1:6000)	< 100 ms
Number of face templates supported	6000
Accuracy	FRR = 98.6% when FAR = 0.001%

The preceding algorithm capability indicators are all measured based on an actual image data set (resolution of 480 x 640), 8GB memory, and quad-core Inter(R) Core(TM) i5-3210M CPU @2.5GHz processor.

## 2.1 Architecture

### 2.1.1 SDK Files

Copy the following files (DLL directory) to the Windows terminal.

File Name	Description
face.dat	Algorithm model file
THFaceImage.dll	Dynamic link library for the algorithm interface
THFaceLive.dll	Dynamic link library for the algorithm interface
THFacialPos.dll	Dynamic link library for the algorithm interface

AMTInfraredFace.dll	Low-level algorithm interface dynamic library
AMTNIRFace.dll	Dynamic library of near-infrared face interface
AMTFaceCap.dll	Dynamic link library for underlying interfaces of face capturing process.
libamtsensorcore.dll	Dynamic link library for underlying communication interfaces of the device
sqlite3.dll	Dynamic link library containing the command-line tools used for managing the SQLite database

## 2.1.2 Development Setup

### SDK dynamic library files can be copied and installed directly

Before installing AMTFaceLite SDK, please make sure that the operating system, system configuration, or Windows portable terminal device meets the requirements for software operation.

Copy related files such as AMTNIRFace.dll, AMTInfraredFace.dll, AMTFaceCap.dll, THFacialPos.dll, THFaceLive.dll, THFacelImage.dll, face.dat, libamtsensorcore.dll, sqlite3.dll and other related files from the AMTFaceLite SDK to the path specified by the user.

## 2.1.3 USB Information

### USB dongle

The AMTNIRFACE12.0 algorithm uses a dongle for user authorization. The dongle is usually built into face recognition devices. Therefore, you do not need an external dongle.

## 2.2 Programming Guide

This section describes the key processes of face recognition to help developers understand the face registration and verification/identification processes implemented by the AMTNIRFACE12.0 algorithm.

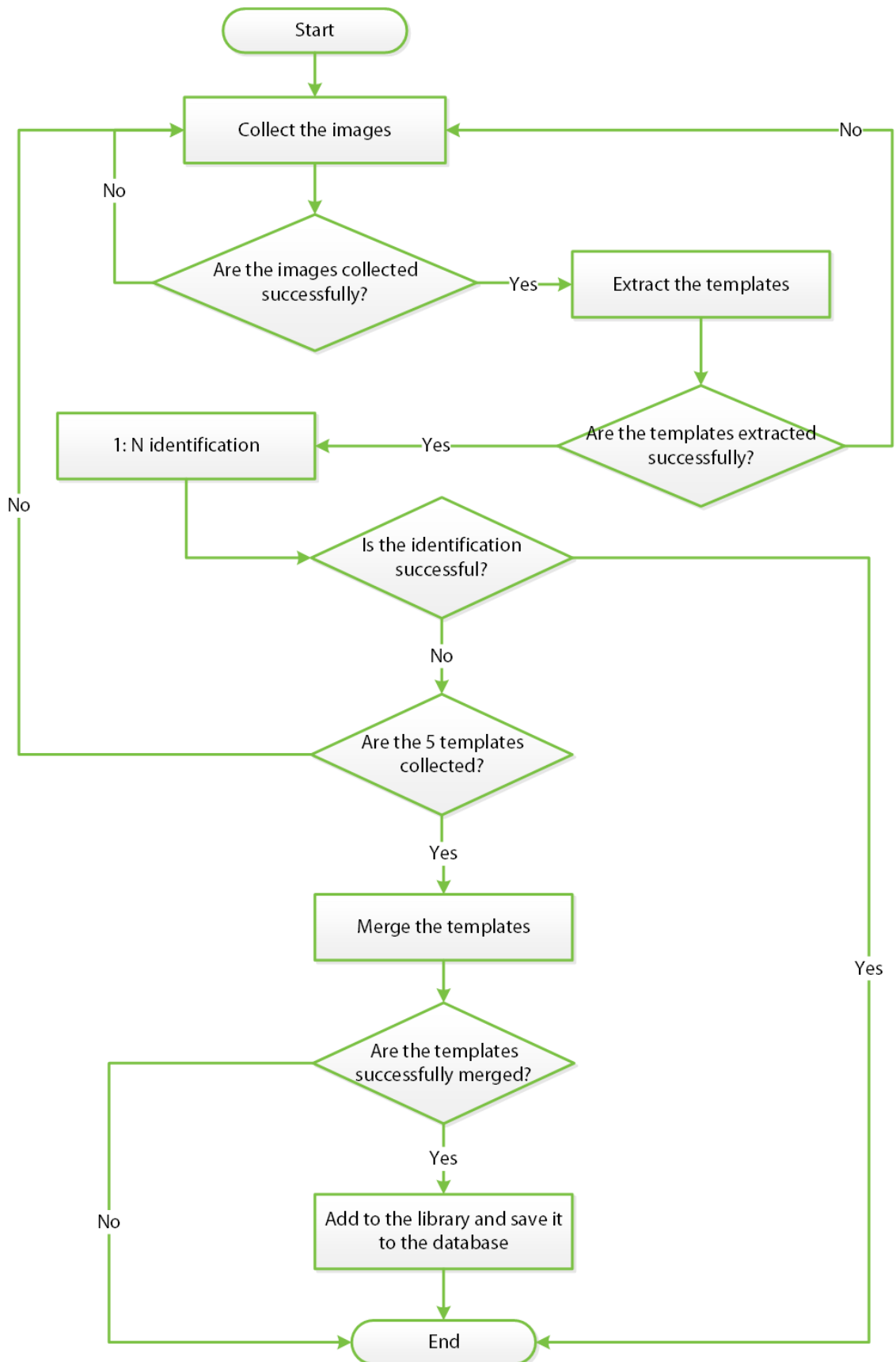
### 2.2.1 Registration Process

In the face registration process, the face recognition application must capture five

verification/identification templates and merge them into a registered template.

For more details about different types of templates, see the [SDK Interface Description](#).

### Registration Process Flow Using 1:N Identification



## Process Description:

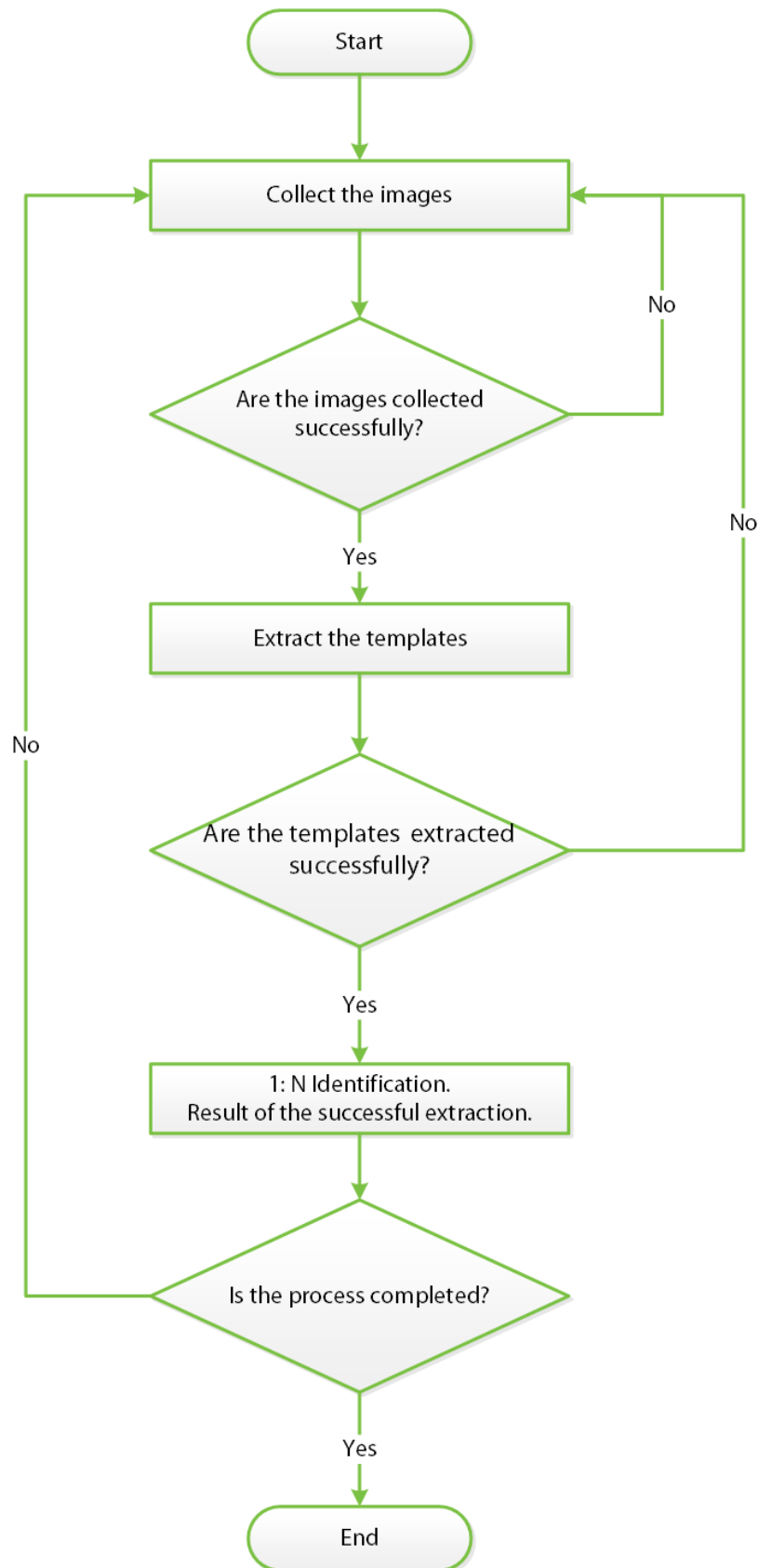
- The application calls the face capturing SDK to capture the face images.
- Once the face images are captured successfully, the application calls the extract function `AMTNIRFace_ExtractFromGrayscaleData` to extract the templates.
- Then the application calls the `AMTNIRFace_DBIdentify 1:N` function to determine whether the current extracted template has been registered.
- And, if it has been registered, the application returns a message and ends the registration process.
- And if less than five templates have been captured, the application continues to capture the next template.
- After capturing five templates, the application merges the templates into a registered template. If the registration fails, the application returns a message and ends the registration process.
- If the registration succeeds, the application calls the `dbAdd` function to add the registered template to the database.
- And thus, ends the process.

## 2.2.2 Verification/Identification Process

### 1:N Identification Process

To implement 1:N face identification, it is required to add all the registered templates to the database. It is recommended to call the `AMTNIRFace_DBAdd` function to add all registered templates to the database after successful algorithm initialization.

### Identification Process Flow



## Process Description

- The application calls the face capturing SDK to capture the face images.
- After the face image is captured successfully, the application calls the AMTNIRFace\_ExtractFromGrayscaleData function to extract a template.
- The application calls the AMTNIRFace\_DBIdentify 1:N function to compare the current template with registered templates.
- And once the registered template is identified, the application ends the registration process.



## 3 SDK Interface Description

### 3.1 NIR Face Template Format Description

Template type	Data length	Description
Verification/Identification template	21072 bytes	Pre-registered or verification/identification template
Registered template	28992 bytes	Registered or Registration template

### 3.2 Near-Infrared Face Interface

AMTNIRFace.dll dynamic library is a dynamic library of Near Infrared Face Interface, mainly used for extraction, registration, and verification/identification of near-infrared face templates.

#### 3.2.1 AMTNIRFace.dll

##### Function List

Function Interface	Description
<a href="#">AMTNIRFace_Version</a>	Gets the SDK version number
<a href="#">AMTNIRFace_Init</a>	Initializes the algorithm resources
<a href="#">AMTNIRFace_Terminate</a>	Releases the algorithm resources
<a href="#">AMTNIRFace_ExtractFromGrayscaleData</a>	Extracts a verification/identification template from 256-gray scale pixel data
<a href="#">AMTNIRFace_GetTemplateQIt</a>	Gets the quality of a face verification/identification template
<a href="#">AMTNIRFace_Verify</a>	Performs the 1:1 face verification
<a href="#">AMTNIRFace_DBVerifyByID</a>	Performs 1:1 verification with the specified faceID
<a href="#">AMTNIRFace_MergeRegTemplate</a>	Merges the verification/identification templates into a registered templates
<a href="#">AMTNIRFace_DBAdd</a>	Adds the registered template to the database
<a href="#">AMTNIRFace_DBDel</a>	Removes the specified face template from the database
<a href="#">AMTNIRFace_DBClear</a>	Clears the database
<a href="#">AMTNIRFace_DBCount</a>	Gets the total number of face templates stored in

	the database
<a href="#">AMTNIRFace_DBIdentify</a>	Performs 1:N face Identification
<a href="#">AMTNIRFace_GetFacePosition</a>	Gets the position coordinates of the near-infrared face
<a href="#">AMTNIRFace_DetectAndGetPos</a>	Face detection and face position acquisition
<a href="#">AMTNIRFace_GetLiveness</a>	Face live detection

## AMTNIRFace\_Version

### Function Syntax

```
int __stdcall AMTNIRFace_Version(char* version, int* size);
```

### Description

Gets the SDK version number.

### Parameters

Parameter	Description
version	<b>Out:</b> Returns the version number (recommended to pre-allocate 128 bytes, enough to use)
size	<b>In:</b> Version memory size (bytes)
	<b>Out:</b> Returns the actual version length

### Returns

See the [Error Code](#)

### Example

```
char szVer[128] = {0};
int len = 128;
ret = AMTNIRFace_Version(szVer,&len);
.....
```

### Remarks

Click [here](#) to view the Function List.

## AMTNIRFace\_Init

### Function Syntax

```
int __stdcall AMTNIRFace_Init(void** context);
```

### Description

Initializes the algorithm resources.

### Parameters

Parameter	Description
context	<b>Out:</b> Algorithm instance pointer

### Returns

See the [Error Code](#)

### Example

```
.....  
void* pInstanceContext = NULL;  
ret = AMTNIRFace_Init(&pInstanceContext);  
.....
```

### Remarks

Click [here](#) to view the Function List.

## AMTNIRFace\_Terminate

### Function Syntax

```
int __stdcall AMTNIRFace_Terminate(void* context);
```

### Description

Releases the algorithm resources.

### Parameters

Parameter	Description
context	<b>In:</b> Algorithm instance pointer

### Returns

See the [Error Code](#)

### Remarks

Call this function at the end of the program.

Click [here](#) to view the Function List.

## AMTNIRFace\_ExtractFromGrayscaleData

### Function Syntax

```
int __stdcall AMTNIRFace_ExtractFromGrayscaleData
(
    void* context,
    unsigned char* rawImage,
    int width,
    int height,
    unsigned char* verTemplate,
    int *cbVerTemplate,
    int expmode,
    int *exp
);
```

### Description

Extracts a verification/identification template from 256-gray scale pixel data.

### Parameters

Parameter	Description
context	<b>In:</b> Algorithm instance pointer
rawImage	<b>In:</b> Grayscale image bit depth 8-bit original image data (256-gray

	scale pixel data)
width	<b>In:</b> Image width
height	<b>In:</b> Image height
verTemplate	<b>Out:</b> Returns the face verification/identification template data
cbVerTemplate	<b>In:</b> vertmp memory allocation size
	<b>Out:</b> Returns the actual data length of verTemplate verification/identification template
expmode	<b>In:</b> Exposure mode (0 for registration, 1 for recognition)
exp	<b>Out:</b> Exposure value of the camera to be adjusted

### Returns

See the [Error Code](#)

### Remarks

- It is recommended to pre-allocate 21072 bytes for face verification/identification template data.
- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

## AMTNIRFace\_GetTemplateQIt

### Function Syntax

```
int __stdcall AMTNIRFace_GetTemplateQIt
(
    void* context,
    unsigned char* verTemplate,
    int* score
);
```

### Description

Gets the quality of the face verification/identification template (supports only the verification/identification template, and not the registration template generated by AMTNIRFace\_MergeRegTemplate).

**Parameters**

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
verTemplate	<b>In:</b> Face verification/identification template data
score	<b>Out:</b> Return the quality score of the corresponding face template (score range: 0 to 255)

**Returns**

See the [Error Code](#)

**Remarks**

- This interface is for reference only, there may be errors.
- Face quality score, the recommended threshold is: 50
- verTemplate can only be the verification/identification template data.

Click [here](#) to view the Function List.

**AMTNIRFace\_MergeRegTemplate****Function Syntax**

```
int __stdcall AMTNIRFace_MergeRegTemplate
(
    void* context,
    unsigned char*verTemplates,
    int mergedCount,
    unsigned char* pMergeTemplate,
    int* cbMergeTemplate
)
```

**Description**

Combines the 5-verification/identification template data into one registered template data.

**Parameters**

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
verTemplates	<b>In:</b> Verification/Identification template data (Supports 5 templates that are required to be merged into a one-dimensional array, it is recommended to pass only 5 verification/identification templates)
mergedCount	<b>Out:</b> Number of verification/identification template data (It is recommended to transfer 5 verification/identification templates, and only supports up to 5)
pMergeTemplate	<b>Out:</b> Registration template synthesized by multiple verification/identification templates (the generated template is used when AMTNIRFace_DBAdd is added)
cbMergeTemplate	<b>In:</b> pMergeTemplate memory allocation size
	<b>Out:</b> Returns the actual pMergeTemplate data length

### Returns

See the [Error Code](#)

### Remarks

- The face registration template suggests pre-allocating 28992 bytes.
- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

## AMTNIRFace\_Verify

### Function Syntax

```
int __stdcall AMTNIRFace_Verify
(
    void* context,
    unsigned char* regTemplate,
    unsigned char* verTemplate,
    int* score
);
```

### Description

Performs the 1:1 face verification.

## Parameters

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
regTemplate	<b>In:</b> Registration template data
verTemplate	<b>In:</b> Verification template data
score	<b>Out:</b> Returns the corresponding verification score

## Returns

See the [Error Code](#)

## Remarks

- Verification score range: 1~1000.
- Verification score threshold recommended value: 575.
- The interface score returns the corresponding verification score value, and the application layer determines the verification threshold.

Click [here](#) to view the Function List.

## AMTNIRFace\_DBVerifyByID

### Function Syntax

```
int __stdcall AMTNIRFace_DBVerifyByID
(
    void *context,
    const unsigned char*verTemplate,
    const char *faceID,
    int *score,
    bool IsAdapt,
    unsigned char*adaptFeature,
    int *cbAdaptFeature
);
```

### Description



Performs the 1:1 verification with the specified faceID.

### Parameters

Parameter	Description				
context	<b>In:</b> Algorithm face instance pointer				
verTemplate	<b>In:</b> Verification template data				
faceID	<b>In:</b> The specified face ID				
score	<b>Out:</b> Return the corresponding verification score				
IsAdapt	<b>In:</b> Whether the registration template needs to be updated. <table border="1" data-bbox="539 719 1098 813"> <tr> <td>true</td> <td>means enable self-learning</td> </tr> <tr> <td>false</td> <td>means disable self-learning</td> </tr> </table>	true	means enable self-learning	false	means disable self-learning
true	means enable self-learning				
false	means disable self-learning				
adaptFeature	<b>Out:</b> Return to the registration template after learning.  It is recommended to pre-allocate 28992 bytes of memory (the returned registration template only needs to be updated to its own application database, and the algorithm is automatically updated to the 1:N bottom library)				
cbAdaptFeature	<b>In:</b> Memory size allocated by adaptFeature (number of bytes) <b>Out:</b> Returns the actual length of the adaptFeature				

### Returns

See the [Error Code](#)

### Example

```
int ret = -1;
int score = 0;
char szFaceID[256] = "faceid";
unsigned char *adaptTemplate = new unsigned char[28992];
memset(adaptTemplate,0,28992);
int cbAdaptTemplate = 28992;
ret = AMTNIRFace_DBVerifyByID(context,
verTemplate,szFaceID,&score,true,adaptTemplate,&cbAdaptTemplate);
if(adaptTemplate)
{
delete [] adaptTemplate;
adaptTemplate = NULL;
}
```

```
}
```

### Remarks

- Verification score range: 1~1000.
- The recommended minimum score is 575.
- If the length of the self-learning registration template returned by cbAdaptFeature is equal to 0, then it means that the self-learning registration template is not successfully generated.
- If the returned length of the self-learning registration template is greater than 0, then it means that the self-learning registration template is successfully obtained and automatically updated to the 1:1 library.
- The interface score returns the corresponding verification score value, and the application layer determines the verification threshold.

Click [here](#) to view the Function List.

## AMTNIRFace\_DBAdd

### Function Syntax

```
int __stdcall AMTNIRFace_DBAdd(void* context, char* faceID);
```

### Description

Adds a registered template to the database.

### Parameters

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
faceID	<b>In:</b> Face ID

### Returns

See the [Error Code](#)

### Remarks

- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

## AMTNIRFace\_DBDel

### Function Syntax

```
int __stdcall AMTNIRFace_DBDel(void* context, char* faceID);
```

### Description

Removes the specified face template from the database.

### Parameters

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
faceID	<b>In:</b> Face ID

### Returns

See the [Error Code](#)

### Remarks

- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

## AMTNIRFace\_DBClear

### Function Syntax

```
int __stdcall AMTNIRFace_DBClear(void* context);
```

### Description

Clears the database.

**Parameters**

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer

**Returns**

See the [Error Code](#)

**Remarks**

- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

**AMTNIRFace\_DBCount****Function Syntax**

```
int __stdcall AMTNIRFace_DBCount(void* context, int* count);
```

**Description**

Gets the total number of face templates stored in the database.

**Parameters**

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
count	<b>Out:</b> Returns the total number of templates stored in the high-speed buffer

**Returns**

See the [Error Code](#)

**Remarks**

- This interface is a non-thread safe interface.

Click [here](#) to view the Function List.

## AMTNIRFace\_DBIdentify

### Function Syntax

```
int __stdcall AMTNIRFace_DBIdentify
(
    void* context,
    const unsigned char*verTemplate,
    char *faceID,
    int* score,
    bool IsAdapt,
    unsigned char*adaptFeature,
    int *cbAdaptFeature
);
```

### Description

Performs the 1:N face identification.

### Parameters

Parameter	Description				
context	<b>In:</b> Algorithm face instance pointer				
verTemplate	<b>In:</b> Identification templates				
faceID	<b>Out:</b> Returns the face ID				
score	<b>Out:</b> Returns the face identification score				
IsAdapt	<b>In:</b> Whether the registration template needs to be updated. <table border="1" data-bbox="539 1585 1098 1709"> <tr> <td>true</td> <td>Means enable self-learning</td> </tr> <tr> <td>false</td> <td>This means disable self-learning</td> </tr> </table>	true	Means enable self-learning	false	This means disable self-learning
true	Means enable self-learning				
false	This means disable self-learning				
adaptFeature	<b>Out:</b> Returns to the registration template after learning. It is recommended to pre-allocate 28992 bytes of memory (the returned registration template only needs to update to its own application database, and the algorithm is automatically updated to the 1:N library)				
cbAdaptFeature	<b>In:</b> Memory size allocated by adaptFeature (number of bytes) <b>Out:</b> Returns the actual length of the adaptFeature				

## Returns

See the [Error Code](#)

## Example

```
int ret = -1;
int score = 0;
char szFaceID[256] = {0};
unsigned char *adaptTemplate = new unsigned char[28992];
memset(adaptTemplate,0,28992);
int cbAdaptTemplate = 28992;
ret = AMTNIRFace_DBIdentify(context,
verTemplate,szFaceID,&score,true,adaptTemplate,&cbAdaptTemplate);
if(adaptTemplate)
{
delete [] adaptTemplate;
adaptTemplate = NULL;
}
```

## Remarks

- Identification score range: 1~1000.
- The recommended minimum score is 585.
- This interface is a non-thread safe interface.
- If the length of the self-learning registration template returned by cbAdaptFeature is equal to 0 then it means that the self-learning registration template is not successfully generated.
- If the returned length of the self-learning registration template is greater than 0, then it means that the self-learning registration template is successfully obtained and automatically updated to the 1:N Bottom library.
- The interface score returns the corresponding identification score value, and the application layer determines the identification threshold.

Click [here](#) to view the Function List.

## AMTNIRFace\_GetFacePosition

**Function Syntax**

```
int __stdcall AMTNIRFace_GetFacePosition
(
    void* context,
    int *positions,
    int count
);
```

**Description**

Gets the position coordinates of the near-infrared face.

**Parameters**

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
positions	<b>Out:</b> Face coordinates
count	<b>In:</b> positions memory allocation size (it is recommended to allocate 12 int data)

**Returns**

See the [Error Code](#)

**Remarks**

- positions return value description:
- positions[0]~positions[7] Four coordinate points of the rectangular frame of the near-infrared face: p0.x p0.y p1.x p1.y p2.x p2.y p3.x p3.y. (The coordinates of the upper left corner of the rectangular frame of the face are arranged clockwise).

<b>positions[8]</b>	X coordinate of the left eye
<b>positions[9]</b>	Y coordinate of the left eye
<b>positions[10]</b>	X coordinate of the right eye
<b>positions[11]</b>	Y coordinate of the right eye

Click [here](#) to view the Function List.

**AMTNIRFace\_DetectAndGetPos**

**Function Syntax**

```
int __stdcall AMTNIRFace_DetectAndGetPos
(
    void* context,
    unsigned char* grayIrr,
    unsigned char* bgrColor,
    int width,
    int height,
    int *yaws,
    int *pitches,
    int*rolls,
    int *points,
    int len
)
```

**Description**

Face detection and face position acquisition.

**Parameters**

Parameter	Description				
context	<b>In:</b> Algorithm face instance pointer				
grayIrr	<b>In:</b> Original image data with 8-bit grayscale image bit depth.				
bgrColor	<b>In:</b> Original image data with a 24-bit BGR image bit depth				
width	<b>In:</b> Image width				
height	<b>In:</b> Image height				
yaws	<b>Out:</b> <table border="1"> <tr> <td>yaws[0]</td> <td>is the infrared face yaw value</td> </tr> <tr> <td>yaws[1]</td> <td>is the visible light face yaw value (allocate 2 arrays of int type length)</td> </tr> </table>	yaws[0]	is the infrared face yaw value	yaws[1]	is the visible light face yaw value (allocate 2 arrays of int type length)
yaws[0]	is the infrared face yaw value				
yaws[1]	is the visible light face yaw value (allocate 2 arrays of int type length)				
pitches	<b>Out:</b> <table border="1"> <tr> <td>pitches[0]</td> <td>is the infrared face pitch value</td> </tr> <tr> <td>pitches[1]</td> <td>is the visible light face pitch value (allocating 2 arrays of int type length)</td> </tr> </table>	pitches[0]	is the infrared face pitch value	pitches[1]	is the visible light face pitch value (allocating 2 arrays of int type length)
pitches[0]	is the infrared face pitch value				
pitches[1]	is the visible light face pitch value (allocating 2 arrays of int type length)				
rolls	<b>Out:</b>				



	<table border="1"> <tr> <td>rolls[0]</td> <td>is the infrared face roll value</td> </tr> <tr> <td>rolls[1]</td> <td>is the visible light face roll value (allocate 2 arrays of int type length)</td> </tr> </table>	rolls[0]	is the infrared face roll value	rolls[1]	is the visible light face roll value (allocate 2 arrays of int type length)
rolls[0]	is the infrared face roll value				
rolls[1]	is the visible light face roll value (allocate 2 arrays of int type length)				
points	<p><b>Out:</b></p> <table border="1"> <tr> <td>points[0]~points[7]</td> <td>Four coordinate points of the rectangular frame of near infrared face</td> </tr> <tr> <td>points[8]~points[15]</td> <td>Four coordinate points of the rectangular frame of near infrared face</td> </tr> </table> <p>The four coordinate points p0.x p0.y p1.x p1.y p2.x p2.y p3.x p3.y of the rectangular frame of the face are arranged in order (from the coordinates of the upper left corner of the rectangular frame of the face are arranged clockwise)</p>	points[0]~points[7]	Four coordinate points of the rectangular frame of near infrared face	points[8]~points[15]	Four coordinate points of the rectangular frame of near infrared face
points[0]~points[7]	Four coordinate points of the rectangular frame of near infrared face				
points[8]~points[15]	Four coordinate points of the rectangular frame of near infrared face				
len	<b>In:</b> Points array size, allocate 16 arrays of int type length				

**Returns**

See the [Error Code](#)

**Remarks**

- This interface is a non-thread safe interface

Click [here](#) to view the Function List.

**AMTNIRFace\_GetLiveness****Function Syntax**

```
int __stdcall AMTNIRFace_GetLiveness
```

```
(
    void* context,
    unsigned char*grayIrr,
    unsigned char* bgrColor,
    int width,
```

```
    int height,  
    float* fScores  
)
```

### Description

Face live detection.

### Parameters

Parameter	Description
context	<b>In:</b> Algorithm face instance pointer
grayIr	<b>In:</b> Original image data with 8-bit grayscale image bit depth.
bgrColor	<b>In:</b> Original image data with a 24-bit BGR image bit depth.
width	<b>In:</b> Image width
height	<b>In:</b> Image height
fScores	<b>Out:</b> Liveness score When the binocular is alive (fScores[0] is the infrared live value; fScores[1] is the visible light live value)

### Returns

See the [Error Code](#)

### Remarks

- This interface is a non-thread safe interface.
- You must call the AMTNIRFace\_DetectAndGetPos interface before calling this interface.
- Recommended liveness threshold is 0.7

Click [here](#) to view the Function List.

## Appendix

### Appendix 1: Error Code

Error Code	Description
0	Successful operation
-1	Image size conversion error, face detection failure
-3	No face detected
-5	Failed to synthesize registration template
-8	Algorithm library memory allocation error
-15	Feature extraction failed
-103	No such faceid in the database (no such faceid in the cache)
-105	The feature of the faceid in the database is invalid (in the high-speed buffer)
-106	Duplicate added faceid
-200	Database is full (cache area)
-1000	Dongle error
-1001	Algorithm library initialization failed
-1002	Algorithm library is not initialized
-1003	Invalid handle
-1004	Null pointer
-1005	The interface is not supported
-1006	Invalid parameter
-1007	Face detection failed during live detection
-1008	Not enough memory allocated
-1012	The face index is invalid
-1015	Failed to allocate memory
-1020	Failed to load algorithm library
-1021	Failed to initialize visible light face detection engine
-1023	Failed to initialize visible light live detection engine
-1024	The algorithm did not detect the near-infrared face before the live detection
-1025	The algorithm did not detect the visible light face before the live detection

## Appendix 2: Glossary

The following definitions will help you understand basic functions of a near-infrared face recognition application and complete integrated development of such an application.

### **Verification/Identification template**

Verification/Identification templates are used for 1:1 or 1:N face verification/identification or merged into a registered template for face registration.

#### **1:1 face verification**

1:1 face verification, also called face verification, is a process of verifying whether a user has a valid identity based on the user ID and face template or determining whether a registered template and several verification templates are extracted from the same face.

#### **1:N face identification**

1:N face identification, also called face recognition, is a process of determining whether a user exists in the system based on the face of the user, without the user ID. Specifically, the application looks up the database of registered face templates based on the input face template and returns the name of the user meeting the threshold, face similarity degree, and other related information.

### **Registered template**

The face registration template returned by `AMTNIRFace_MergeRegTemplate`, or the self-learning registration template returned by `AMTNIRFace_DBIdentify` and `AMTNIRFace_DBVerifyByID`.

### **Registered face**

The face recognition module/collector captures five face images of the same user to extract verification/identification templates, merges the verification/identification templates into a registered template, and then loads it to the backend database as a registered face for subsequent face recognition.

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